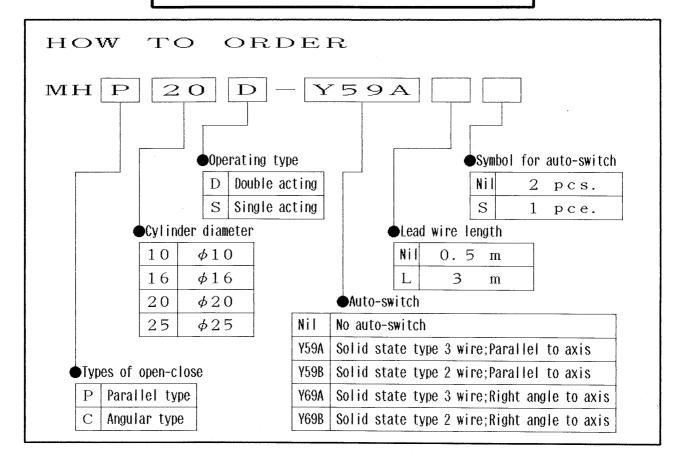


PNEUMATIC GRIPPER "AIR CHUCK" MH SERIES INSTRUCTION MANUAL



= I NDEX =

1. Mounting style of Air Chuck. • • • • • • • • • • • • Page 1
2. Mounting procedure of auto-switch. · · · · · · · · · · · · Page 2
3. Piping · · · · · · · · · · · · · · · · · ·
4. Installation adjustment of Air Chuck Page 3
5. Gripping point. · · · · · · · · · · · · · · · · · · ·
6. Effective gripping force for parallel type gripper Page 6
7. Effective gripping force for angular type gripper Page 7

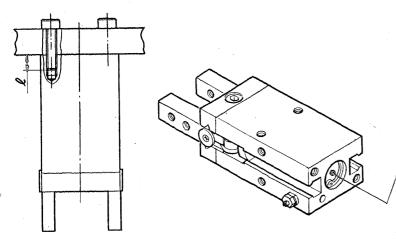
SMC CORPORATION

1. Mounting style of Air Chuck.

MH series Air Chuck can be mounted from 3 directions.

Appropriate direction can be selected to suit intended machinery or workpiece.

(1) To mount direct axis type (body tap)

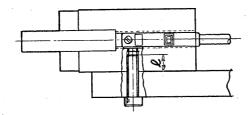


wodel	bolt	MAX.tight- ening tor- que kgf·cm	of engage-
MHP10,MHC10	M3x0.5	9	6
MHP16,MHC16	M4x0.7	21	8
MHP20,MHC20	M5x0.8	44	10
MHP25,MHC25	M6x 1	74	12

• Holes at end of body can be used for positioning.

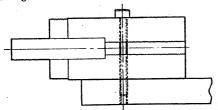
Model Hole dia. Hole depth MHP10,MHC10 ϕ 11H9 $^+$ 0.043 1.5 MHP16,MHC16 ϕ 17H9 $^+$ 0.043 1.5 MHP20,MHC20 ϕ 21H9 $^+$ 0.057 1.5 MHP25,MHC25 ϕ 26H9 $^+$ 0.052 1.5

②Side mounting type (body tap, body through hole) Body tap use



•In case, body tap is used.			
wodel	bolt	MAX.tight- ening tor- que kgf·cm	of engage-
MHP10,MHC10	M3x0.5	7	5
MHP16,MHC16	M4x0.7	21	8
MHP20,MHC20	M5x0.8	44	10
MHP25,MHC25	M6x 1	74	12

Body through hole use

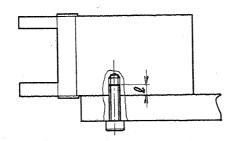


•In case, bo	dy through	hole is used.
Model	using bolt	MAX.tightening torque kgf·cm
MHP10,MHC10	M2.5x0.45	5
MHP16,MHC16	M 3 x0.5	9
MHP20,MHC20		21
MHP25,MHC25	M 5 x0.8	44

Note) When auto-switch is desired, only body tap type can be used. Care should be taken not to push main body of the switch by end of bolt, length of engagement;! should be no more than figures stated in table as shown.

Model	MAX.length of engagement; L mm
MHP10,MHC10	5
MHP16,MHC16	8
MHP20,MHC20	10
MHP25,MHC25	12

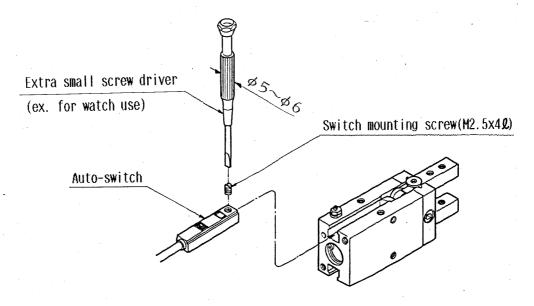
③Vertical mounting type (body tap)



Model	bolt	MAX.tight- ening tor- que kgf·cm	of engage-
MHP10,MHC10	M3x0.5	9	6
MHP16,MHC16	M4x0.7	16	6.5
MHP20, MHC20	M5x0.8	34	8
MHP25,MHC25	M6x 1	60	10

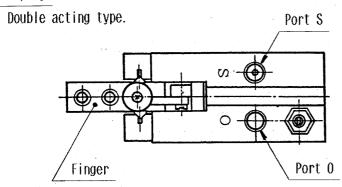
2. Mounting procedure of auto-switch.

To mount auto-switch, insert auto-switch into mounting groove of Air Chuck as shown in lower illustration. After mounting position is determined, secure by tightening fitting screw provided.

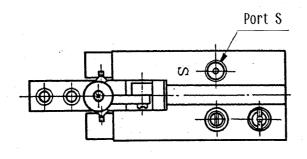


Note) To tighten auto-switch fitting screw, use extra small screw driver of grip dia. approx. 5-6mm. Advised tightening torque is approx. $0.5-1kgf \cdot cm$. When touch feeling is obtained, rotate 90° to reach the required torque.

3. Piping.



Single acting type.



- Piping portPort S;Port to close finger
- · Piping port size

Model	Piping port size
MHP10D, MHC10D	M3x0.5
MHP16D, MHC16D	
MHP20D, MHC20D	M5x0.8
MHP25D, MHC25D	

Port 0; Port to open finger

- Piping port
 Port S;Port to close finger
- · Piping port size

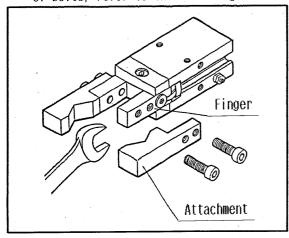
Model	Piping port size
MHP10S, MHC10S	M3x0.5
MHP16S, MHC16S	
MHP20S, MHC20S	M5x0.8
MHP25S, MHC25S	

- · Pipe fittings. -use SMC miniature pipe fittings (M3, M5 series) or one-touch fittings (M5 size).
- Pipes to be connected should be air-flushed thoroughly and care should be taken to ensure dirt or cutting-chips do not enter into Air Chuck assembly.

4. Installation adjustment of Air Chuck.

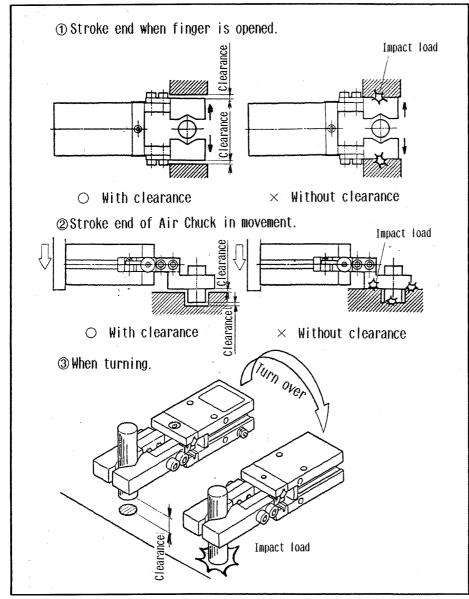
1)Precautions to fit attachment.

When mounting attachment to finger, it should be carried out holding finger by spanner or other means so that the tightening force is not transmitted to the finger guide mechanism. For tightening torque of bolts, refer to the following table.



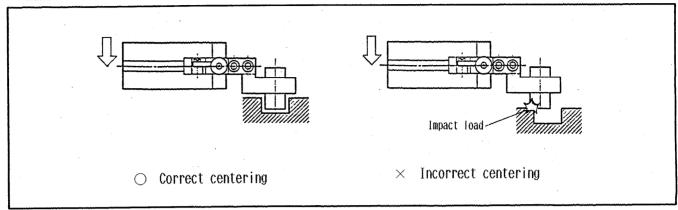
Model	Fixing	Max.tightening
nouer	bolt	torque kgf.cm
MHP10, MHC10	M2.5x0.45	3.2
MHP16, MHC16	M3x0.5	6
MHP20, MHC20	M4x0.7	14
MHP25, MHC25	M5x0.8	29

2) Adjust the device not to receive external force on its finger and some clearance should be kept at stroke end of the finger between finger and the other object.



Appropriate clearance should be kept at finger not to receive force except gripping workpiece, particularly when workpiece is gripped, not to crash to other object at stroke end of Air Chuck movement, Lateral load comes on to finger repeatedly or impact load comes on may cause finger to loosening or damage. It is often happens when Air Chuck is turned little variation of length of workpiece may cause to crash at downward stroke end of turning movement. It should be cared.

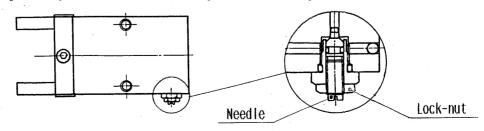
Before inserting workpiece, centering should be carried out thoroughly not to add unnecessary force to finger. Particularly in test run, keep manual force or air cylinder pressure low to operate and make sure no existence of shock and safety.

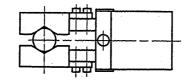


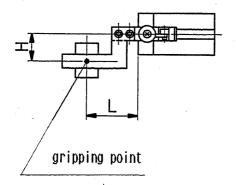
- Adjustment of open-close speed of the finger.
 Adjust open-close finger speed not to unnecessarily fast.
- · How to adjust open-close finger speed.

Double acting ty	/pe Speed can be adjusted by bui	It-in needle. Table below can be referred as a guide.
Single acting ty	/pe Connect speed controller *1 -in style.	to close side port of the finger and use it as meter
		* ₁ SMC's speed controller AS1000F or equivalent.
	Back turns from the needle	
Model	fully closed. (*2)	st_{2} When needle is tightened to slightly touch bottom
MHP10D, MHC10D	1/4 - 1/2	
MHP16D, MHC16D	1/2 - 1	
MHP20D, MHC20D	1 - 1 1/2	
MHP25D, MHC25D	1 1/2 - 2	

- In case angular type, in order to avoid impact to the portion of finger base due to inertia moment adjustment may be needed for making operating speed slower according to the length of attachment.
- If open-close speed is unnecessarily fast, impact force on finger becomes too great and will shorten its life.
- OAdjusting procedure for needle.
 - Rotate needle valve clockwise to close and anti-clockwise to open.
 Rotate needle valve clockwise to decrease finger closing speed and anti-clockwise to increase.
 - Rotate needle anti-clockwise, drop-preventing function to stop it.
 Do not attempt to rotate further.
 - · Upon completing adjustment, ensure lock-nut is tightened correctly.





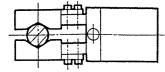


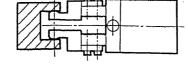
L; length of gripping point

H; length of overhang

- Molding point of workpiece is recommended to follow conditions stated in graphs right hand side for L; holding distance subject to working pressure, and H; over-hang quantity.
- ©Used Chuck outside of recommended area stated in graphs for holding point of workpiece, load coming on finger and guide part becomes excessively great and so may cause to malfunction of the finger or shorten its life.

The products are designed for external work holding. For internal work holding applications please contact us.

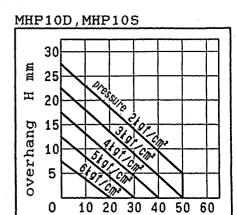




o external work holding

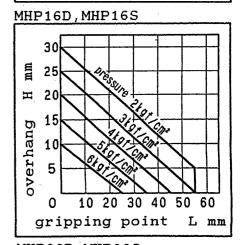
imes internal working holding

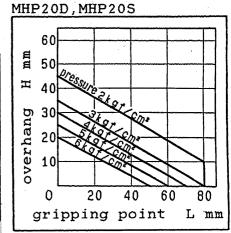
Limitting range of gripping point.

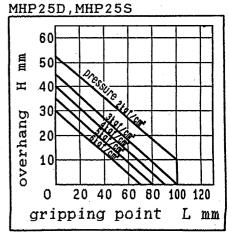


gripping point

L mm

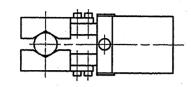


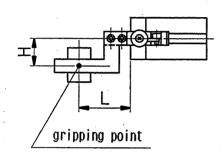




Gripping Point

Effective Gripping Force

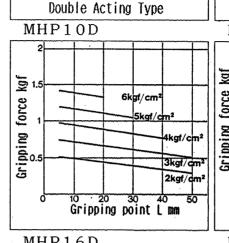


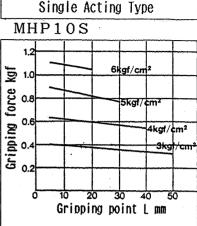


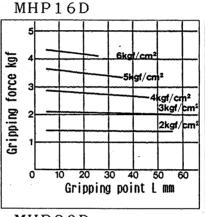
Gripping point; The length of L and length of H should be used within the limits described on P5.

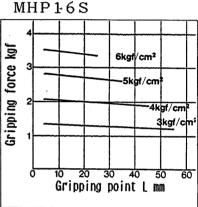
Guidelines for The Selection of Air Chuck Model with Respect to Component Weight

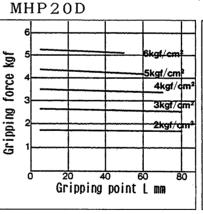
- ◆Selection of the correct model depends upon the component weight, the coefficient of friction between the chuck attachment and the component, and their respective configurations. A model should be selected with a gripping force of 10 to 20 times of the component weight.
- ●If high accelleration, high decelleration or impact are encountered during component transportation then a further margin of safety should be considered.

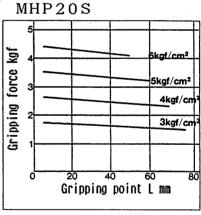


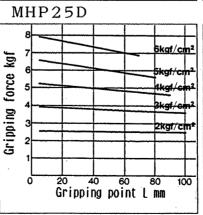


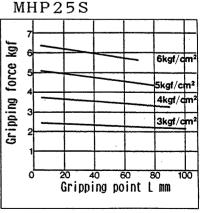






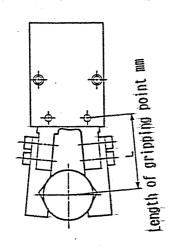


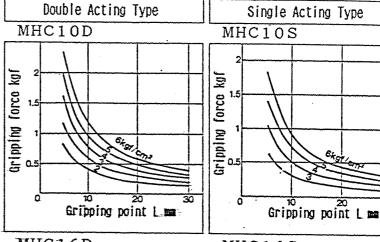




Gripping Point

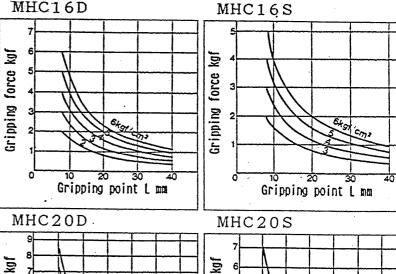
Effective Gripping Force



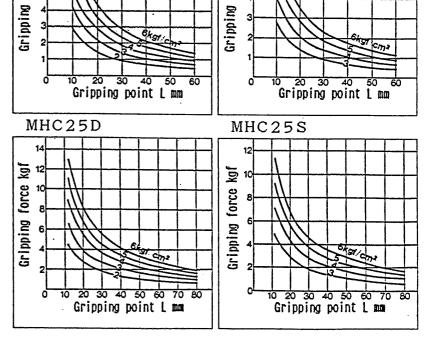


Guidelines for The Selection of Air Chuck Model with Respect to Component Weight

- ◆Selection of the correct model depends upon the component weight, the coefficient of friction between the chuck attachment and the component, and their respective configurations. A model should be selected with a gripping force of 10 to 20 times of the component weight.
- ●If high accelleration, high decelleration or impact are encountered during component transportation then a further margin of safety should be considered.



force



force